

# ConStance: Modeling Annotation Contexts to Improve Stance Classification

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## Abstract

Manual annotations are a prerequisite for many applications of machine learning. However, weaknesses in the annotation process itself are easy to overlook. In particular, scholars often choose what information to give to annotators without examining these decisions empirically. For subjective tasks such as sentiment analysis, sarcasm, and stance detection, such choices can impact results. Here, for the task of political stance detection on Twitter, we show that providing too little context can result in noisy and uncertain annotations, whereas providing too strong a context may cause it to outweigh other signals. To characterize and reduce these biases, we develop ConStance, a general model for reasoning about annotations across information conditions. Given conflicting labels produced by multiple annotators seeing the same instances with different contexts, ConStance simultaneously estimates gold standard labels and also learns a classifier for new instances. We show that the classifier learned by ConStance outperforms a variety of baselines at predicting political stance, while the model’s interpretable parameters shed light on the effects of each context.

## 1 Introduction

When annotators are asked for objective judgments about a text (e.g., POS tags), the broader context in which the text is situated is often irrelevant. However, many NLP tasks focus on inference of factors beyond words and syntax. For example, the present work addresses the task of detecting political stance on Twitter. We ask an-

notators to determine whether a given Twitter user supports Donald Trump or Hillary Clinton. However, inferring something about a *user* from a single tweet that she writes may prove difficult. Prior work on stance has relied on annotations collected this way (Mohammad et al., 2016b), but individual tweets do not always contain clear indicators.

One solution to this issue is to supply the annotator with more information about the user. For example, for the similar task of classifying a Twitter user’s political affiliation, Cohen and Ruths (2013) display the user’s last 10 tweets. Nguyen et al. (2013), studying gender and age, ask annotators to label users by leveraging all information available in their profile. Thus, researchers have provided a range of contexts (or more broadly, information conditions) to annotators in an attempt to balance annotators’ exposure to the data needed for accuracy with reasonable costs in terms of time, money and cognitive load.

However, while scholars routinely make such decisions about what information to show annotators, they rarely examine how such decisions actually impact annotations. The first contribution of this paper (Section 3) is to show that, at least for political stance detection on Twitter, displaying different kinds of context to annotators yields significantly different annotations *for the same user*. As a result of these discrepancies, the accuracy of models trained on these annotations varies widely.

While it is possible one could select a “best” context for a given task, our results suggest that doing so *a priori* is difficult and that, moreover, different contexts provide complementary information. What we would prefer, instead, is a model that *learns* how contexts affect annotators and *combines* annotations from multiple contexts to create gold standard labels.

Fortunately, prior work suggests mechanisms for such a model. Typically in annotation tasks,

each item is judged by several annotators, and the resulting labels are aggregated, usually by majority vote, to create a gold standard. As an alternative to majority vote, Raykar et al. (2010) develop an elegant probabilistic approach for learning to aggregate labels produced by annotators of varying quality. Their model jointly estimates gold standard labels (in the form of probability scores), infers annotator error rates, and learns a classifier for use on out-of-sample data.

Our second contribution (Section 4) is an extension of Raykar et al.’s model to handle labels not only created by annotators of varying quality, but also produced under *information conditions* of varying quality. We call this model ConStance<sup>1</sup>. Like Raykar et al. (2010), who find that even low-quality annotators are useful, we find that low-quality contexts can be useful. Specifically, we find that the classifier produced from our model performs better than any classifier trained by majority vote from the same labels. Furthermore, the model provides an unsupervised method for comparing the information conditions by examining their respective error patterns.

Intuitively, ConStance performs a role analogous to boosting for annotations: for an arbitrary task, it permits collection of labels that capture different aspects of the instances at hand, then combines them automatically to determine which are more reliable and to produce a classifier that takes all this into account.

## 2 Annotating Political Stance

### 2.1 Political Stance Detection

Stance detection is defined as the task of determining whether an individual is in favor of, against, or neutral towards a target concept based on the content they have generated (Mohammad et al., 2016b). It is related to but distinct from sentiment analysis: a given document can have negative sentiment but a positive stance towards a particular target, or vice versa. Further, for stance detection, the target need not be explicitly mentioned. These points are best illustrated via example: the tweet “I hope that the Democrats get destroyed in this election!” has a negative sentiment (towards Democrats), and (therefore, most likely) implies a

positive stance towards Donald Trump.

As a case study for how context impacts annotations, we focus on political stance detection on Twitter—specifically, determining stance towards Hillary Clinton and Donald Trump during the 2016 U.S. election season. This task illustrates the challenges of annotation, since individual tweets are often ambiguous with respect to stance, contexts on Twitter are inherently fractured, and differing contexts can make annotators lean in different directions.

Note that a user’s stance, as we use the term in this paper, is a latent (and stable) property of the user. However, short of interviewing the user, we can never be completely certain of her stance. As such, the examples here and evaluations later rely on the authors’ best estimates of stance, using all available information.

A user’s tweets, in turn, may or may not reveal her stance. This means that, by our definitions, an annotator might accurately perceive no stance in a tweet, yet have their annotation be considered incorrect with respect to the user’s true stance. We would consider this case an annotator error caused by lack of context.

As examples of the task, consider annotating the following three tweets: (i) “*crooked Hillary - #lockHerUp,*” (ii) “*Lester thinks he can control the crowd when he can’t even keep Trump on topic lmao,*” and (iii) “*Settling in for #debatenight Hoping to hear an adult conversation.*” In the case of (i), a passing familiarity with American politics gives us high confidence that the author is pro-Trump. The tweets in (ii) and (iii) are more ambiguous, but the authors’ stances become clearer with access to varying forms of context. For (ii), a Pepe the frog image (a symbol used by the American alt-right movement) in the user profile reveals that the user is probably a Trump supporter. Similarly, for (iii), a profile description that reads “*Stereotypical Iowan who enjoys Hillary Clinton, progressive politics. Chair of CYDIWomen. Previously @HillaryForIA and @NARAL.*” suggests support for Clinton and distaste for Trump.

In order to explore the effects on annotation quality of providing these kinds of context to annotators, we crowd-source annotations for a set of tweets and vary the additional information provided to annotators. For ease of comparison with related work and within our own study, we associate each user with a single anchor tweet. Thus, both annotators and classifiers are asked to deter-

<sup>1</sup> Replication materials for this work, including code for ConStance, are available at <https://github.com/kennyjoseph/constance>. The paper’s Supplementary Material can also be accessed there.

mine the stance of a user using data from one particular time window.

## 2.2 Data

We collected tweets during the general election season (7/29/2016–11/7/2016) from over 40,000 Twitter users we had previously matched to voter registration records. Matching Twitter users to voter registrations (using methods similar to Barberá, 2016; Hobbs et al., 2017) helps ensure that the accounts we study are controlled by humans, and it supplies additional demographic variables: gender, race and party registered with.

We identified as a political tweet any tweet that mentioned the official handle for Donald Trump (@realDonaldTrump) or Hillary Clinton (@HillaryClinton), or that contained one or more of the following terms or hashtags: Hillary, Clinton, Trump, Donald, #maga, #imwithher, #debatenight, #election2016, #electionnight. We removed all reply tweets, quote tweets and tweets that directly retweeted the candidates. Finally, we kept only those users who posted at least three political tweets.

From these users, we sampled 562 political tweets for crowd-sourced stance annotation, selecting at most one tweet per user. These tweets were all sampled from users who were registered Democrats or Republicans. Half the tweets were paired with Hillary Clinton as the target, the other half with Donald Trump. We also sampled and set aside an additional 250 + 318 tweet/target pairs to use as development and validation data, respectively (see Section 2.5).

## 2.3 Annotation Task

We used Amazon Mechanical Turk (AMT) for annotation. Annotators were presented a triplet of {tweet, target, context} and were asked to make their decisions on a 5-point Likert scale, ranging from “Definitely Opposes [target]” to “Definitely Supports [target]”. Both prior work (Mohammad et al., 2016b) and our pilot studies suggested confusion between options for a tweet’s irrelevance towards a target and the tweet’s neutrality towards the target, so we used the center of the scale for both options. For this paper, we use a narrower three-point scale formed by merging the “Definitely” and “Probably” options.

Further, while tweets were annotated with respect to different targets, we combine all annotations into a single task by assuming that “anti-

Context	Displays the anchor tweet plus ...
No Context	No additional information
Partial Profile	Profile image, name, and handle
Full Profile	Author’s profile image, name, handle, and description
Previous Tweets	Author’s two most recent tweets <i>in general</i> prior to the anchor
(Previous) Political Tweets	Author’s two most recent <i>political</i> tweets prior to the anchor
Political Party	Political affiliation (if any) from the author’s voter registration

Table 1: Descriptions of the six contexts (information conditions) presented to the annotators.

Trump” means “pro-Clinton”, and vice-versa. This assumption seems reasonable given that the voting population was strongly polarized during the general (post-primary) election season, and it doubles the amount of data we can use to train the models. Thus, throughout this work the labels we use are taken from the set {“Support Trump / Oppose Clinton” = -1, “Neutral / I don’t know” = 0, “Oppose Trump / Support Clinton” = 1}.

## 2.4 Contexts Studied

Each of the 562 “anchor” tweets was annotated under six different *contexts* (also referred to as information conditions) described in Table 1. (The Supplementary Material provides visual examples of each.) We collected at least three annotations for each tweet/condition pair. Every AMT worker was shown 40 different tweets, one by one, randomly distributed across contexts. Two additional artificial tweets were used to control for task competency.

We selected the conditions in Table 1 based on two factors. First, we included conditions that varied in how much we expected them to impact annotations. For example, we expected the partial profile information to have a relatively small effect, and political party a larger one. Second, we restricted our options to sets of information that we believed would minimally impact task completion times. We confirmed this empirically by regressing the (logged) time to completion for each annotator on the number of tweets she saw for each context, finding no significant effects from any context.

## 2.5 Gold Standard Labels

Ideally, we would evaluate annotation quality and downstream performance by comparing to ground truth. Unfortunately, ground truth is difficult to

characterize for tasks as subjective as stance detection or sentiment analysis (Passonneau and Carpenter, 2014; DiMaggio, 2015). In light of this, we constructed our own labels, using all available information about users, and we use them as an approximation of ground truth.

We constructed these labels in order to evaluate downstream classification performance, and they cover a set of users not shown to the AMT workers. Given our resource constraints and the numerous (at least 18), often conflicting labels already available for tweets shown to AMT workers, we did not create definitive labels for that set.

To create these “gold standard” (GS) labels, we considered all information found on the user’s Twitter timeline, including everything AMT annotators could see, plus friend/following relationships, all of their previous tweets, demographics from the voter file, etc. Anecdotally, we found certain cases time-consuming to investigate, which argues for continuing to limit how much information we ask annotators to consider. All gold standard labels were agreed upon by at least two authors, who first labeled the data independently and then came together to discuss disagreements.

Our GS set consists of 318 users (with their associated anchor tweets). Each user is assigned a label from the tertiary Trump/Neutral/Clinton scale. Another 250 manually labeled accounts were used for model development but are not part of reported results. The GS is approximately equally divided among registered Democrats, registered Republicans, and people not registered with either party; the last category includes self-declared Independents and voters not affiliated with any party. We include this third set in order to ensure the models generalize beyond registered Democrats and Republicans.

### 3 Annotation Quality For Individual Contexts

In this section, we examine how annotator agreement varies depending on the context in which the labels were obtained, and how classifiers trained on majority-vote labels from each individual context, as well as on labels from all contexts combined, perform on the GS. First, we introduce the classifier and features used for the latter task, then discuss results for agreement and classifier performance.

#### 3.1 Classifier, Labels, Features, & Evaluation

For each of the six contexts separately, we construct labels with which to train a classifier. Training labels are constructed using majority vote; we also tried weighting the training instances to match the distribution of labels, but it did not perform as well. We also construct a seventh set of labels using all annotations from all conditions. We then train a classifier on each set of labels. We use Random Forest models, as they outperformed regularized logistic regression and SVMs with linear kernels on the development set. Note that the only difference among the models in this section is the *labels* they are *trained* on.

The feature set used, shown in Table 2, is meant as a straightforward representation of the information seen by annotators; parts of it follow Ebrahimi et al. (2016). We construct three types of features for each tweet: text, sentiment and user features. For text features, we collapse the anchor tweet plus all additional textual context seen by any annotator into a single string, then compute various n-grams from it. For sentiment, we compute various scores from the anchor tweet alone. For user features, we include the user’s race and gender, which annotators might have learned from the user’s profile picture. Note that because we want models to generalize beyond registered Democrats or Republicans, we *do not* include a feature for political party.

Classifier performance on the GS is measured, following prior work (Mohammad et al., 2016a; Ebrahimi et al., 2016), on the average of the F1 scores on the two classes of interest (“Clinton” and “Trump”). Additionally, we report the average log-loss (the negative log-likelihood, according to the classifier, of the true label). Log-loss and F1 can be seen as complementary measures: whereas F1 evaluates the quality of the ranking of test instances, log-loss evaluates the quality of their individual probability estimates. To compute the probability estimate from a Random Forest, we compute mean class probabilities across all trees.

To assess the statistical significance of differences between two models, we first obtain probability estimates for all GS items. For log-loss, we use a Mann-Whitney test on the scores from the two models being compared. For F1, we create 1000 bootstrap iterations of the sample, compute the average F1 of each, and run a non-parametric difference-in-means test, using 95% confidence

Category	Data Source	Feature Representation
Text	Anchor tweet, previous (political) tweets, profile description	Character n-grams ( $n \in [3, 5]$ ), word n-grams ( $n \in [1, 3]$ ). Preprocessing: only use tokens appearing $\geq 10$ times, apply tf-idf weighting.
Sentiment	Anchor tweet	VADER score (Hutto and Gilbert, 2014)
		Dictionary approach (Joseph et al., 2017): valence, dominance & arousal scores
User	Voter registration record	Race, gender

Table 2: Features used in classification.

Model	Agreement	Log-Loss	Avg F1
No Context	0.84	0.72	0.61
Partial Profile	0.83	0.71	0.68
Full Profile	0.82	0.69	0.62
Previous Tweets	0.84	0.65	<b>0.71</b>
Political Tweets	<b>0.88</b>	<b>0.61</b>	0.70
Political Party	<b>0.88</b>	0.63	0.68
All Combined	0.77	0.62	<b>0.71</b>

Table 3: Inter-annotator agreement, then performance of classifier trained on majority vote labels. (Best possible is 1 for agreement and F1, 0 for log-loss.)

intervals.

### 3.2 Effects of the Contexts

Before evaluating classification results, we consider annotator agreement within each context, calculated like Mohammad et al. (2016b) as the average, across tweets, of the percentage of annotations that match the majority vote. As shown in Table 3, annotators shown No Context achieve an agreement score of 0.84, similar to the 0.8185 reported by Mohammad et al. (2016b). Relative to this baseline, some contexts increase agreement more than others. As one might expect, Previous Political Tweets and Political Party show the strongest signals. Their effects are statistically ( $p < .01$ , Mann-Whitney test) and practically significant, increasing the number of labels having *full* agreement by 15% and 10%, respectively.

However, annotators shown different contexts did not necessarily converge to the same labels. Notice the low agreement for the All Combined condition: the majority labels held stronger majorities within any individual context than across all of them. In fact, if we look at the six majority vote labels for each tweet, only in 43% of the tweets are these labels in full agreement. At the end of Section 5, we return to the question of why agreement was so low across conditions, with the help of parameters estimated by ConStance.

In the classification task, the results in Table 3 further suggest that Previous Political Tweets

serves as the strongest single context. There is a good case to be made for choosing this individual context, which is statistically significantly better than many others. For example, providing annotators with Previous Political Tweets provides a statistically significant increase in both average F1 scores and log-loss (with  $p < .01$ ) over both the No Context and Full Profile conditions. Perhaps most noteworthy is that the All Combined classifier, created from the naive combination of all annotations, is no better than the classifiers from the individual conditions.

To summarize, results suggest that providing annotators with appropriate additional context can improve annotation quality, as measured via annotator agreement and downstream classification performance. However, it was not obvious in advance which context would be most helpful, and performing such an analysis as this requires the time-intensive construction of better “gold standard” labels against which to check the labels already being outsourced to annotators. In addition, the heterogeneity of the labels produced in different contexts suggests that the contexts provide diverse signals we might be able to leverage; however, simply combining all the annotations does not result in improvements.

## 4 ConStance: General Unified Model

The prior section thus suggests that it may be better to limit a priori decisions and instead to leverage multiple kinds of context during annotation. Like Raykar et al. (2010) assumes for annotators, we might expect (and indeed find) that even those contexts that turn out to be worse on some metrics still might be useful for other purposes. Here, we present a model for such an approach.

ConStance learns a classifier for *items*. For our purposes here, an item is a user together with their anchor tweet and the additional information from which features were derived (see Table 2); more broadly, it is whatever we choose to put into the feature vector. One could choose a differ-

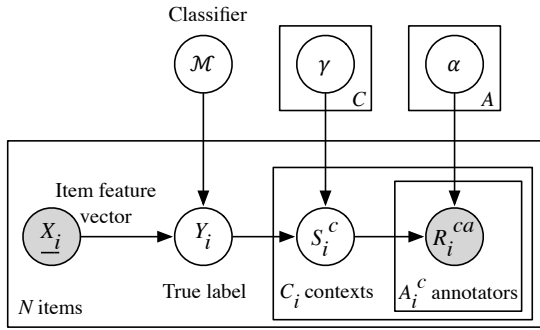


Figure 1: Graphical model for ConStance.

Var.	Meaning
$X_i$	Feature vector of item $i$
$Y_i$	Latent true label of item $i$
$S_i^c$	Latent context-specific label of item $i$ after noise from context $c$
$R_i^{ca}$	Label given by annotator $a$ to item $i$ in context $c$
$V$	Set of values for labels and annotations: $\{-1, 0, 1\}$
$N$	# of items, indexed by $i$
$C$	Set of contexts, indexed by $c$
$A$	Set of annotators, indexed by $a$
$\mathcal{M}$	Learned classifier
$\gamma^c$	$V \times V$ parameter matrix for context $c$
$\alpha^a$	$V \times V$ parameter matrix for annotator $a$
$\mathcal{D}$	All observed data: all values of $X_i$ and $R_i^{ca}$
$Z$	All latent variables: all values of $Y_i$ and $S_i^c$
$\theta$	All model parameters: $\mathcal{M}, \gamma, \alpha$
$T_i$	All latent variables for item $i$ : $(Y_i, S_i^c)$
$\tau_{i(y,s)}$	Current estimate of all latent values for item $i$ : $p(Y_i = y, S_i^c = s \mid \mathcal{D}, \theta)$

Table 4: Model variables.

ent setup; for example, an item could be a user and ten anchor tweets. However, the current arrangement allows for straightforward comparison to prior stance work on Twitter (Mohammad et al., 2016a).

Note that in general, the features need not be restricted to those annotators could have seen. Rather, they could include anything useful to a classifier. Note also that the feature set provided to ConStance is the same used by the baseline models; only the models themselves differ.

#### 4.1 Overview

The model we develop is shown in Figure 1. There are  $N$  items to be labeled. Each item can be viewed in up to  $C$  different contexts. Finally, there are  $A$  total annotators labeling the items; each annotator sees multiple items. Each item can have a different number of annotations, produced by any assignment of annotators and information conditions to items. In our dataset, every item is labeled

in 6 conditions (every  $|C_i| = 6$ ), and within every context, every item is labeled by at least 3 annotators (every  $|A_i^c| \geq 3$ ).

The model’s generative story works as follows. Item  $i$  has feature vector  $X_i$  and a “true” label  $Y_i \in V$ . The relationship between  $X_i$  and  $Y_i$  can be described by some model  $\mathcal{M}$ , which we will ultimately learn. When the item is viewed with context  $c$ , the item’s true label  $Y_i$  is transformed by noise into a “context-specific” label  $S_i^c \in V$ . In other words, the true label may appear differently when seen through the lens of each context. The variable  $S_i^c$  represents what an ideal annotator would say about item  $i$  given only as much information as is preserved by context  $c$ .

The “noise” introduced by context  $c$  is described by parameter  $\gamma^c$ . The parameter  $\gamma^c$  is a  $V \times V$  matrix of transition probabilities from true labels to context-specific labels. These probabilities depend only on  $Y_i$  and  $\gamma^c$ , not on the item’s features  $X_i$ .

Importantly, annotators themselves are also imperfect. When annotator  $a$  sees item  $i$ , she may also distort the label she sees,  $S_i^c$ , into the observed annotation  $R_i^{ca} \in V$ . The annotator-specific noise process is described by parameter  $\alpha^a$ , another  $V \times V$  transition matrix.

For a better understanding of the role of  $\gamma^c$  (and by analogy,  $\alpha^a$ ), consider the depictions in Figure 2. The matrix on the top left refers to the No Context condition. Its top row describes what an annotator with perfect judgment would think about a user whose true label is Trump [supporter], with no context. The top left cell, with a value around 0.65, is the probability the annotator would think Trump; the lighter middle cell, with a value around 0.35, is the probability she would think Neutral/Don’t know; and the probability she would think Clinton is almost 0.

#### 4.2 Learning

Like Raykar et al. (2010), we perform inference using Expectation Maximization (EM). A full derivation is provided in the Supplementary Material; here, we sketch the main steps.

The model’s incomplete data likelihood function, Eq. (1), describes the joint probability, across all items, of  $Y_i$ , all values of  $S_i^c$ , and all values of  $R_i^{ca}$  assuming  $X_i$  is known and fixed. Uppercase denotes random variables; lowercase, specific values. In line (2), we substitute in the equivalent

model parameters.

$$\begin{aligned}
p(\mathcal{D}|\theta, X) &= \prod_{i=1}^N \sum_y^V p(Y_i = y | \underline{x}_i, \mathcal{M}) \prod_c^{C_i} \\
&\sum_s^V p(S_i^c = s | y, \gamma) \prod_a^{A_i^c} p(r_i^{ca} | s, \alpha) \quad (1) \\
&= \prod_{i=1}^N \sum_y^V \mathcal{M}_y(\underline{x}_i) \prod_c^{C_i} \sum_s^V \gamma_{ys}^c \prod_a^{A_i^c} \alpha_{sr}^a \quad (2)
\end{aligned}$$

The EM derivation is difficult because both  $Y_i$  and  $S_i$  are unobserved. Our solution is to treat the latent variables as a block, describing their joint configuration with a single term  $T_i = (Y_i, S_i)$ . In our data, since  $|C_i| = 6$ ,  $T_i$  can take on  $7^{|V|}$  possible values, a number small enough to enumerate over when we need to marginalize out  $T_i$ .

We define membership indicator variables  $T_{i(y\underline{s})} \in \{0, 1\}$  such that  $T_{i(y\underline{s})} = 1$  if  $T_i$  has the specific values  $(y, \underline{s})$ . During learning, we use analogous variables  $\tau_{i(y\underline{s})} \in [0, 1]$  to represent the posterior probabilities of each configuration:  $\tau_{i(y\underline{s})} = p(T_{i(y\underline{s})} = 1 | \mathcal{D}, \theta)$ . The expected value of the complete data log-likelihood is:

$$\begin{aligned}
\mathbb{E}_Z[\ell(\mathcal{D}, Z|\theta, X)] &= \sum_{i=1}^N \sum_y^V \left( \sum_{s_1^1}^V \dots \sum_{s_i^{C_i}}^V \right) \\
\tau_{i(y\underline{s})} &(\log p(T_{i(y\underline{s})} | \underline{x}_i, \mathcal{M}, \gamma) + \sum_c^{C_i} \sum_a^{A_i^c} \log \alpha_{sr}^a) \quad (3)
\end{aligned}$$

For the E step, we update the membership estimates  $\tau_{i(y\underline{s})}$  using the current parameters  $\theta$ . With Bayes' rule, each item's new value of  $\tau_{i(y\underline{s})}$  is shown to be the full joint likelihood of item  $i$  (see Eq. (2)) when setting  $Y_i = y$  and  $S_i = \underline{s}$ , divided by the sum, over all possible settings of  $Y_i$  and  $S_i$ , of that same joint likelihood.

For the M step, we update the model parameters using the current membership estimates. To update the classifier  $\mathcal{M}$ , following the guidance of Raykar et al. (2010), we retrain the classifier using the current estimates of  $Y_i$  as weights for items. The estimates of  $Y_i$  can be obtained from  $\tau_{i(y\underline{s})}$  by marginalizing out  $S_i$ , thus  $\mathbb{E}_Z[Y_i = y] = \sum_{s_1^1}^V \dots \sum_{s_i^{C_i}}^V \tau_{i(y\underline{s})}$ . We then use sampling to construct a discrete set of labels for model training based on these weights.

Model	Log-Loss	Avg F1
Best baselines	<i>0.61</i>	<i>0.71</i>
<b>ConStance</b>	<b>0.57</b>	<b>0.77</b>
Ablations		
1. Only Political Tweets	0.59	0.73
2. Context Labels Masked	<b>0.57</b>	0.75
3. Annotator Labels Masked	0.65	0.75

Table 5: Classification performance of ConStance and model ablations. Boldface highlights best scores. Significance tests use the the  $p < .05$  level for log-loss. Compared to the best baselines, all scores that appear better are statistically significant. Italics indicate the scores that are significantly worse than ConStance.

To update  $\gamma$  and  $\alpha$ , we maximize them with respect to Eq. (3). For  $\gamma$ , the entry  $\gamma_{ys}^c$  (i.e., row  $y$ , column  $s$  of matrix  $\gamma^c$ ) denotes  $p(S_i^c = s | Y_i = y)$ . Each matrix entry can be updated individually by taking the partial derivative of Eq. (3) and using, as a Lagrange multiplier term, the constraint that the row must sum to 1. The updated value for  $\gamma_{ys}^c$  turns out to be a fraction in which the numerator is the weighted (by  $\tau$ ) number of items having  $Y_i = y$  and  $S_i^c = s$ , and the denominator is the weighted number of items having  $Y_i = y$  (and any value for  $S_i^c$ ). For  $\alpha$ , a similar derivation yields the following update to  $\alpha_{sr}^a$ : the weighted number of labels by annotator  $a$ , in any context, having  $S_i^c = s$  and  $R_i^{ca} = r$ , divided by the weighted number of labels by annotator  $a$ , in any context, having  $S_i^c = s$ .

## 5 Model Results and Discussion

The top portion of Table 5 displays ConStance's performance compared to the best results from Section 3. Using the same experimental setup as Section 3—the model type and features,  $\mathcal{M}$  and  $X$  respectively, are the same as in the baselines—ConStance improves over the best baseline models for each metric. This improvement is statistically significant for both metrics (at the  $p < .05$  level for log-loss). Further, the model converges rapidly, within 5-7 iterations of the EM algorithm and 3-5 minutes on a single machine.<sup>2</sup>

In addition to comparing to the baselines provided in Section 3, we investigate which information the model is leveraging to be successful. We do so by exploring three ablations of the model. Variation #1 (“Only Political Tweets” in Table 5)

<sup>2</sup>As above, a development set is used for coarse hyperparameter tuning; see the Supplementary Material for details.

uses the full model, but only gives it the annotations from the Political Tweets condition. This tests whether simply modeling differences in annotators’ error rates, as Raykar et al. (2010) do, with a single (“best”) context is helpful. We find that it is: the performance of this variation is significantly better on both metrics than the Political Tweets baseline from Table 3.

In the second and third variations, we check whether the effectiveness of ConStance stems from modeling differences between annotators rather than differences in contexts, or vice versa. Variation #2 (“Context Labels Masked”), like #1, models only annotator effects; however, it instead uses the entire set of annotations, treating them as if from a single context (i.e., “masking” context information from the model). Variation #3 (“Annotator Labels Masked”) is the complement of Variation #2: it models differences in contexts, and it uses the entire set of annotations, treating them as if from a single annotator.

The results of the model ablation experiments are three-fold. First, we see that each piece of the model on its own is effective in moving beyond baseline approaches that use only one context or naively combine labels across contexts and annotators (the “All Combined” baseline). All model variations achieve significantly higher Avg. F1 than the baselines, and Variations #1 and #2 improve on log-loss. Second, we see that modeling annotators alone is clearly better than not: not only does Variation #1 outperform the Political Tweets baseline (significantly), but also Variation #2 outperforms the All Combined baseline (significantly) and ConStance outperforms Variation #3 (with significance in one measure). Finally, the best results come from using the full model. Even if the differences between ConStance and the variations are not all statistically significant, modeling both annotators and contexts appears to be the most complete and effective approach.

In addition to model performance, we can also examine what ConStance has learned about the quality of labels from each context. Recall that the model produces a parameter matrix for each context,  $\gamma^c$ , which describes how a context distorts the “true” labels the model assumes. Each  $\gamma^c$  is a transition matrix, so a context that perfectly preserves true labels would show up as the identity matrix; off-diagonal entries show error patterns.

Figure 2 visualizes parameter estimates for  $\gamma$ .

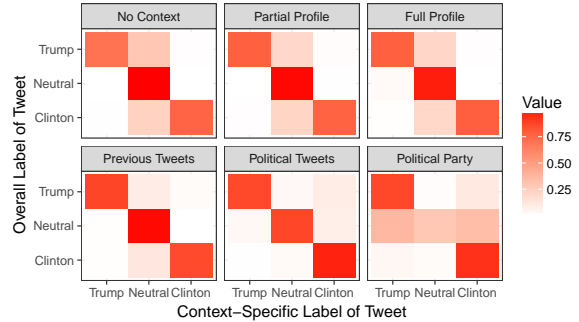


Figure 2: Parameter matrices  $\gamma^c$  learned by ConStance for each context. Darker shading indicates higher values.

We see that in the No Context, Partial Profile and Full Profile conditions, annotators often selected the “Neutral” option ( $x$ -axis) when the model inferred the true label was “Clinton” or “Trump” ( $y$ -axis). This finding is in line with intuitions; annotators who saw these conditions simply lacked enough information to determine any label.

On the other extreme, in the Political Party context, annotators selected “Trump” or “Clinton” too often when the model settled on the “Neutral” option. That is, even when a user’s stance was not clear to annotators in other conditions, annotators who saw political party still inferred stance from the text. Here, one could argue annotators were shown “too much” or “too strong” a context—they saw stance even where the content produced by the user did not suggest one. Indeed, further manual inspection of 90 tweets on which annotations disagreed across contexts implies that annotators who saw political affiliation were often wrong because they focused too little on text content relative to the provided political affiliations.

In presenting these findings, a key point to highlight is that unlike the results of Section 3, Figure 2 was produced without access to any full information labels, which depend on a significant level of manual effort beyond annotations gathered on AMT.

## 6 Related Work

Recent work has shown that cognitive biases such as stereotypes (Carpenter et al., 2016) and anchoring (Berzak et al., 2016) can negatively impact text annotation and resulting models, even for objective tasks like POS tagging (Blodgett et al., 2016). Still, researchers often decide what context to show annotators without rigorously evalu-



ating how their decisions will affect annotations, on tasks from gender identification to political leanings (Chen et al., 2015; Nguyen et al., 2014; Burger et al., 2011; Cohen and Ruths, 2013). Our work suggests an interesting avenue of development towards reducing annotation bias by explicitly modeling it and reducing the need for a priori decisions on which context is best for which particular task.

In doing so, we draw on a large body of work around improving annotation quality for NLP data. Our work aligns with efforts to improve task design (e.g. Schneider et al., 2013; Morstatter and Liu, 2016; Schneider, 2015), and to develop better models of annotation. With respect to the former and specific to Twitter, Frankenstein et al. (2016) show that for the task of labeling the sentiment of reply tweets, annotations vary depending on whether or not the original tweet (being replied to) is also shown. With respect to the latter, several recent models beyond Raykar et al. (2010) have been proposed (Guan et al., 2017; Tian and Zhu, 2012; Wauthier and Jordan, 2011; Passonneau and Carpenter, 2014). However, our work is most similar to efforts outside the domain of NLP, where Dai et al. (2013) have developed a method of switching between task workflows based on annotation quality for particular items, and Nguyen et al. (2016) have developed a Bayesian model similar to ours to study annotation quality for other kinds of slightly subjective tasks.

In a closely related vein, recent work has also considered how text annotations may vary in important ways based on the characteristics of annotators (rather than how the task is posed, as we study here) (Sen et al., 2015). An interesting avenue of future work is to understand the intersection between the design of NLP annotation tasks and the characteristics of the annotating population.

## 7 Conclusion and Future Work

Annotated data serves as a foundational layer for many NLP tasks. While some annotation tasks only require information from short texts, in many others, we can elicit higher-quality labels by providing annotators with additional contextual information. However, asking annotators to consider too much information would make their task slow and burdensome.

In this paper we demonstrate how exposing an-

notators to short contextual information leads to better labels and better classification results. However, different contexts lead to results of different quality, and it is not obvious a priori which context is best, nor—even given ground truth—how to combine labels produced across contexts to exploit the information present in each. We then propose ConStance, a generalizable model that learns the effects of both individual contexts and individual annotators on the labeling process. The model infers (probability estimates for) ground truth labels, plus learns a classifier that can be applied to new instances. We show that this classifier significantly improves classification of political stance compared to the standard practice of training models on majority vote labels.

The focus of this work is on improving both the annotation process for nuanced, context-dependent tasks and the use of the resulting labels. While ConStance’s label estimation can be used in conjunction with any classification method, this paper does not address the optimization of the classifier itself. Thus, while we consider an assortment of contexts and use a rich feature representation, using additional contexts or different features may lead to better performance on stance detection. Finally, the model is versatile enough we could consider treating different tweets as different “contexts” for the same user, augmenting the extensively annotated tweets with other types of data, and, naturally, applying the same framework to other annotation tasks.

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